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A34661-PCT-USA (071308.0244)  
PATENT

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09/937913

## 30 ROCKEFELLER PLAZA

**NEW YORK, NEW YORK 10112**

JC09 Rec'd PCT/PTO 01 OCT 2001

TO ALL WHOM IT MAY CONCERN:

Be it known that WE, PETER SOPP and SIEGBERT STEIDL, citizens of Germany, whose post office addresses are Ottensooser Str. 53, 90482 Nuernberg, Germany; and Schuetzengraben 16D, 91074 Herzogenaurach, Germany; respectively, have made an invention in:

## MASTER CONTROL SYSTEM FOR A ROLLING MILL

of which the following is a

## **SPECIFICATION**

## FIELD OF THE INVENTION

[0001] The invention relates to a master control system for a rolling mill, and particularly a mill train, both of which have at least one rolling stand driven by means of a drive system, and the master control system having an automation device for the open-loop and/or closed-loop control of the rolling stand. The invention also relates to a method of operating a rolling mill, on a mill train, having the aforesaid master control system

## BACKGROUND OF THE INVENTION

[0002] It is customary in the commissioning of individual components of a rolling mill or a mill train to connect said components by a data link to a commissioning computer and to commission them by transferring a program code or operating parameters. After

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completion of this process, this operation is repeated with the next system component. System components in this sense may be, for example, drive systems or automation devices. When individual components, for example defective components, are exchanged, the new component, for example a new automation device or a new drive system, is also correspondingly commissioned.

#### SUMMARY OF THE INVENTION

**[0003]** The object of the present invention is to improve the commissioning process. This object is achieved according to the present invention by a rolling mill which has at least one rolling stand driven by means of a drive system and a master control system with at least one automation device for the open-loop and/or closed-loop control of the rolling stand. The master control system has a commissioning computer for the commissioning of the drive system and of the automation device. According to the method of the present invention, the commissioning of the drive system and of the automation device takes place by means of the commissioning computer. The master control system has at least one bus system for the transmission of operating parameters and/or program code from the commissioning computer to at least one of the components comprising the drive system and automation device. Furthermore, the bus system is designed for the transmission of information necessary for the operation of the rolling mill, and especially the mill train, between the drive system and the automation device.

**[0004]** In a preferred embodiment of the present invention, the master control system has an operator-control computer for monitoring and/or influencing the rolling mill, or the mill train, and the commissioning computer is designed for the commissioning of the

operator-control computer.

**[0005]** In a further preferred embodiment of the present invention, the bus system is designed for the transmission of operating parameters and/or program code from the commissioning computer to the operator-control computer.

**[0006]** In yet another preferred embodiment of the present invention, the bus system is designed for the transmission of information necessary for the operation of the rolling mill, or the mill train, between the operator-control computer and at least one of the components comprising the drive system and the automation device.

**[0007]** Other preferred embodiments of the present invention, include a master control system has at least one first bus system for the transmission of operating parameters and/or program code from the commissioning computer to the automation device with the commissioning computer and the automation device being connected by a data link; and at least one second bus system for the transmission of operating parameters and/or program code to the drive system, with the automation device and the drive system being connected by a data link. The second bus system may also be designed for the transmission of information necessary for the operation of the rolling mill, or mill train, between the automation device and the drive system.

**[0008]** It is also preferred if the master control system has an operator-control computer for monitoring and/or influencing the rolling mill, or mill train, with the operator-control computer being connected to the first bus system by a data link, and the first bus system being designed for the transmission of information necessary for the operation of the rolling mill, or mill train, between the operator-control computer and the automation

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device.

[0009] In yet another preferred embodiment of the invention, the master control system has at least two different types of automation devices and the commissioning computer is designed for the commissioning of both automation devices.

#### BRIEF DESCRIPTION OF THE INVENTION

[0010] Further advantages and details of the present invention will be apparent from the following description of an exemplary embodiment as shown in Figure 1 which shows a master control system.

#### DETAILED DESCRIPTION OF THE INVENTION

[0011] In Figure 1, an industrial Ethernet bus 9 is shown, which connects two identically or differently designed automation devices 5 and 6, an operator-control computer 4 and a commissioning computer 1 to one another by a data link. The industrial Ethernet bus 9 is connected to a standard Ethernet bus 8 via a computer 7. Connected to the standard Ethernet bus 8 are an operator-control computer 2 and a central operator-control computer 3. Parts of the rolling mill (or parts of the mill train) can be operated via the operator-control computers 2 and 4. The interaction of individual system parts of the rolling mill (or mill train) can be operated by means of the central operator-control computer 3. Various actuators or sensors 12, 13, 14, 15 are connected by a data link to the automation device 5 via a bus system 23, which is designed as a Profibus. Furthermore, decentralized peripherals 10 are connected to the automation device 5 via the bus system 23. Various actuators or sensors 16, 17, 18, 19 are connected by a data

link to the automation device 6 via a bus system 24, which is designed as a Profibus. Furthermore, decentralized peripherals 11 are connected to the automation device 6 via the bus system 24. Moreover, various actuators and sensors 20, 21, 22 can be activated and evaluated via the decentralized peripherals 11 and the automation device 6.

**[0012]** The operator-control computers 2, 3, 4, the automation devices 5, 6, the decentralized peripherals 10, 11, the actuators and sensors 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22 and the bus systems 8, 9, 23, 24 serve for the operation of the rolling mill (or mill train). Furthermore, information necessary for the commissioning, such as operating parameters or program codes, i.e., software, are transmitted from the commissioning computer 1 to the automation devices 5, 6, the decentralized peripherals 10 and 11 and to the actuators and sensors 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, and, if appropriate, to the operator-control computers 2, 3, 4. The transmission of the commissioning information takes place via the corresponding bus systems 8, 9, 23 and 24. Furthermore, the commissioning computer 1 may also be used for the development of the master control system.

**[0013]** It is advantageous to provide diagnostic information on the operating capability of the automation devices 5, 6 of the decentralized peripherals 10, 11, of the actuators and sensors 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22, and, if appropriate, of the operator-control computers 2 and 4 some or all of which are transmitted to the operator-control computers 2, 3 and 4. The sensors and actuators 12, 13, 14, 15, 16, 17, 18, 19, 20, 21, 22 serve, by way of example, the open-loop and closed-loop control of one or more of the following: drive systems for rolling stands, cooling sections, coilers or loop lifters.